

# Handling Robot for Picking and Packing MOTOMAN-MPP and MPK Series



# Automated transfer systems for picking and packing processes of food, pharmaceuticals, and cosmetics.



# Picking MOTOMAN- MPP3S, MPP3H

# **High productivity**

The MPP series of robots can be installed in close proximity in a small space. As the best in their class, they also enable high-speed handling<sup>\*1</sup> with a large motion range and improve productivity.

- 150 cpm\*<sup>2</sup> with a 3 kg load and 230 cpm\*<sup>3</sup> with a 1 kg load are possible.
- Allowable inertia of the wrist is 0.017 kg·m<sup>2</sup>, and high-speed handling with two hands is possible.
  - \* 1 : Handling in Adept cycle (25 mm × 305 mm × 25 mm) without positioning limit. Does not include the time for using suction to grab a workpiece.
     \* 2 : Cycle per minute
  - \* 3: With a limit in continuous operations
- Wiring and piping work can be easily performed through the hollow section (80 mm dia.) located at the center of the body.

Flexible and high-speed handling is maximized through combined use of a double conveyor synchronization function, vision function, and production management function.

# Even higher productivity can be achieved with Yaskawa's original robot design

Cycle times can be reduced with shorter suction time in addition to high-speed robot movements. The hollow structure of the robot (first in the industry) enables the installation of air valves inside the parallel link arms. The structure shortens the length of piping drastically, which achieves a reduction in the cycle time.

### Large motion range with a small installation space

- MPP3S Range of motion : 800mm(dia.)×200mm(H) Footprint : 650mm(dia.)
- MPP3H Range of motion : 1300mm(dia.)×300mm(H) (Widest in its class)
   Footprint : 750mm(dia.)

# High level of cleanliness

The MPP series of robots are designed to maintain high level of cleanliness for food handling.

- Ball joints are free of grease because self-lubricating material approved by the Food Sanitation Law of Japan is used.
- Because they can be mounted on ceilings and maintenance is done from the top downwards, damage or contamination of workpieces and conveyors is prevented if a work tool, part, or grease falls during maintenance.
- The surface of the body, excluding arms, is smooth and easy to clean.
- Can be washed with acid- or alkaline-based disinfectant.
- Clean Class: ISO class 5



for cleanroom application by

Fraunhofer IPA.



# Picking MOTOMAN- MPK2F, MPK2F-5



Increased efficiency by transferring and packing many workpieces from a single row or layer at one time.



# **Space-saving installation**

Compact design increases usability in restricted spaces or in high-density layouts.

Shortened maximum Minimized minimum turning radius
 Minimized minimum turning radius
 (Minimum width)
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500 Cycle time\* Cycle time\* 125 •1.1 s 0.6 s 400 (55 cycles/min: 30 kg) (100 cycles/min: 40 kg) 600 90 ÷. 

Motion pattern 1

Motion pattern 2 \*: Does not include the time for grabbing and releasing a workpiece.

### Multi-purpose

With a high-payload, a wide motion range, and a wide variety of the components, the MOTOMAN-MPK50II can be used as a palletizing robot for small workpieces.

- Max. payload: 50 kg Can transfer many workpieces at one time, can operate packing
- Wide motion range (Palletizing also possible) Maximum horizontal reach (T-point): 1893 mm, Vertical motion range: 1668 mm, S-axis turning range: -180° - +180°
- Wide variety of components

One cable (23-core), two air hoses (dia.: 10 mm), and one tube for field-bus cable (dia.: 12 mm) accommodated in hollow arm.

- Protection Class Body: IP54 (optional: IP65), Wrist: IP67
- Options Food-grade lubricant for food machinery



Controller with best functions and performance for handling and assembly applications

### Optimum controller for handling and assembly

Supports robots with a payload of 20 kg or less

Fits in a 19 inch rack and can be installed under conveyors.

- Improved performance and high-speed control obtained by improving resolutions for I/O commands as well as by reducing time for ladder scanning.
- High-speed positioning achieved by suppressing vibration of hands (MPP3S/MPP3H/MPK2F/MPK2F-5).
- Commands specifically designed for workpiece handling with synchronized conveyors.



### **Open controller**

The FS100 robot controller offers an environment and functions that enable users to develop optimum application programs for their own use.

Functions	Descriptions	Remarks
	Allows users to customize application programs for robot control	MotoPlusIDE (development
MotoPlus	$\cdot$ Users can create robot control programs in C and install them in the	environment) is optional.
	controller.	
	Allows users to directly control the FS100 controller from the host	Compatible host computers:
MotomanSync	controller by using the FS100 as servers.	Windows, MP3200 controllers,
Optional	<ul> <li>Robots can be controlled directly from the host computer.</li> </ul>	Rockwell PLC*
	Provide the function to develop application programs for the	
Pendant Customization	programming pendant	
	$\cdot$ WindowsCE application programs developed by users can be	
Optional	incorporated in the programming pendant.	

\*: Compatible with 1756-L61 ControlLogix and 1756-L35E CompactLogix controllers.

Main Hardware	Options
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- Programming pendant
- External axis (max.: 2 axes)
- · I/O module (28 points, NPN or PNP)
- · Counter module (2 channels)
- · Analog input module (8 channels)
- · Analog output module (4 channels)
- Major fieldbus interface boards DeviceNet (master/slave), CC-Link (slave), PROFIBUS (slave), EtherNet/IP (slave, I/O communications)

### Main Optional Functions

- Conveyor synchronization
   Vision function
  - External reference point control
- Relative job

TCP

- Independent control
- Coordinated control
  - ontrol · Search · Automatic backup
- Servo float
- · Energy saving mode (with servomotor turn off limit)
- · Software pendant
- · Network (data transfer, FTP, Ethernet server)
- · Bilingual display (Shown in the required language.)

# 

Low floor-type controller that can be stacked up. The amplifier for three external axes and other options that previously required attachment tools can now be housed inside a standard cabinet, reducing the required space for installation by up to 50%. The safety functions have been strengthened by improving the safety performance of the speed limiting function and tool switching monitoring function.

### Safety

Improved Safety Functions (New and optional)

- The robot position is monitored by a functional safety module equipped with two CPUs, increasing safety.
- Motion is limited to a set area by monitoring the position of the robot and tool.
- The Preventive Maintenance Function for Speed Reducer can detect speed reducer faults. The Preventive Maintenance Function for Hardware can prompt you to replace hardware before it breaks.

### Easy operation

 Editing or prohibiting editing instructions with the programming pendant makes controlling jobs easier.
 (JOB Line Comment-Out Function, JOB Line Edit-Protect Function, JOB Folder Function)



### Space-saving installation

- A safety fence can be installed in an area smaller than the robot motion area to save space.
- Two DX200 robot controllers can be stacked\*. Installation width can be reduced by 30% compared with two DX100 controllers installed side-by-side.
- \*: Some models are excluded.

### Picking & Packing Software MotoPick

MotoPick provides support for picking and packing with the software applications specially designed for those operations. A pattern for the arrangement of workpieces moving on a conveyor or a pattern for picking and placing operation can be easily selected or changed on a computer. This software helps improve overall productivity in conveyor lines.

Optional

### Vision function

The camera connected to a computer running MotoPick can be adjusted and controlled. Data on positions of individual workpieces moving on a conveyor can automatically be obtained with the camera.

### Real time automatic scheduling

The motion patterns of the robot in pick and place applications are controlled based on the position data of workpieces that have been obtained by the camera and transferred to the robot's controller.





# MOTOMAN-MPK2F

2 kg payload, R900 mm maximum reach FS100

### Dimensions Units : mm : P-point Maximum Envelope





Connector for internal user I/O wiring harness: RM15WTRZ-10P (with cap) Matching connector: RM15WTPZ-10S\*HIROSE\* (provided by users)

4-Inlet

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4-PT1/8







View C

### Manipulator Specifications

Model		MOTOMAN-MPK2F	Allowable	B-axis (wrist pitch/yaw)	3.5 N•m
Type Floor mount, built-in base type Ceiling mount, built-in base type		YR-MPK002F-A00	Moment	T-axis (wrist twist)	1.5 N•m
		YR-MPK002F-A01	Allowable Inertia	B-axis (wrist pitch/yaw)	0.065 kg⋅m²
Control	led Axis	5 (vertically articulated)	(GD <sup>2</sup> /4)	T-axis (wrist twist)	0.012 kg⋅m²
Payload	1	2 kg	Mass		72 kg
Repeatability*1		±0.5 mm		Temperature	0°C to +40°C
	S-axis (turning)	-170° - +170°	-	Humidity	20% to 80%RH (non-condensing)
Range of Motion	L-axis (lower arm)	-120° - +120°		Vibration	4.9 m/s² (0.5 G) or less
	U-axis (upper arm)	-102° - +282°	- Amplent	Others	<ul> <li>Free from corrosive gas or liquid, or</li> </ul>
	B-axis (wrist pitch/yaw)	-150° - +150°	Conditions		explosive gas or liquid
	T-axis (wrist twist)	-270° - +270°	-		<ul> <li>Free from exposure to oil, or dust</li> </ul>
	S-axis (turning)	5.59 rad/s, 320°/s	-		Free from excessive electrical noise (plasma)
Maximu	L-axis (lower arm)	5.76 rad/s, 330°/s	Power Requirements*2 2.0 kVA		2.0 kVA
Speed	U-axis (upper arm)	5.76 rad/s, 330°/s	*1 : Conforms to ISO 9283.		
Speed	B-axis (wrist pitch/yaw)	6.63 rad/s, 380°/s	*2 : Varies in a	accordance with applic	ations and motion patterns.
	T-axis (wrist twist)	34.9 rad/s, 2000°/s	Note: SI units are used for the specifications.		

**MOTOMAN-MPK2F-5** 

5 kg payload, R900 mm maximum reach FS100

### Dimensions Units : mm



### Manipulator Specifications

Model		MOTOMAN-MPK2F-5		
		YR-MPK002F-A10	YR-MPK002F-A20	
Туре		(Floor mount, built-in	(Ceiling mount, built-in	
		base type)	base type)	
Controlled Axis		5 (vertically	articulated)	
Payload		5	5 kg	
Repeatability*1		±0.5	mm	
Range of	S-axis (turning)	-170° -+170°		
	L-axis (lower arm)	-120° -+120°		
	U-axis (upper arm)	-102° - +60°	-60° - +240°	
WOUGH	B-axis (wrist pitch/yaw)	-15° - +15°*3		
	T-axis (wrist twist)	-270° - +270°		
	S-axis (turning) 5.59 rad/s, 320°/s		/s, 320°/s	
Maximum Speed	L-axis (lower arm)	5.76 rad/s, 330°/s		
	U-axis (upper arm)	5.76 rad/s, 330°/s		
	B-axis (wrist pitch/yaw)	6.63 rad/	′s, 380°/s	
	T-axis (wrist twist)	34.9 rad/s, 2000°/s		

Allowable	B-axis (wrist pitch/yaw) 2.26 N·m		
Moment	T-axis (wrist twist)	0 N•m	
Allowable Inertia	B-axis (wrist pitch/yaw)	0.065 kg·m <sup>2</sup>	
(GD <sup>2</sup> /4)	T-axis (wrist twist)	0.012 kg⋅m²	
Mass		72 kg	
	Temperature	0°C to +40°C	
	Humidity	20% to 80%RH (non-condensing)	
Ambiant	Vibration	4.9 m/s <sup>2</sup> (0.5 G) or less	
Conditiono	Others	<ul> <li>Free from corrosive gas or liquid, or</li> </ul>	
Conditions		explosive gas or liquid	
		Free from exposure to oil, or dust	
		Free from excessive electrical noise (plasma)	
Power Requirements*2		1.5 kVA	

\*1 : Conforms to ISO 9283.

- \*2 : Varies in accordance with applications and motion patterns.
- \*3: Motion range of the B-axis is the angle of the B-axis to the ground.
- In some postures, the motion range of the B-axis may be limited depending on the relative angle to the upper arm.

Note: SI units are used for the specifications.

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# MOTOMAN-MPP3S/MPP3H

3 kg payload, maximum reach 800 mm (dia.)  $\times 200 \text{ mm}$  (H) (MPP3S) 1300 mm (dia.)  $\times 300 \text{ mm}$  (H) (MPP3H)

FS100



### Manipulator Specifications

Model MOTOMAN-		MPP3S	MPP3H	
Туре		YR-MPP003S-A00	YR-MPP003H-A00	
Controlled Axis		4 (parallel link)		
Payload		3 kg		
Repeatab	ility*1	±0.1 mm		
Repeatab	ility (T-axis rotation)	±1 arc-n	±1 arc-min or less 10 mm (dia.) × 200 mm (H)   1300 mm (dia.) × 300 mm (H)*4	
Range of Motion		800 mm (dia.) × 200 mm (H)	1300 mm (dia.) × 300 mm (H)*4	
Cycle Time for $25 \times 305 \times 25$ mm		1 kg: 230 cpm*5		
motion pattern		3 kg: 150 cpm		
	Range of Motion	-360° ·	- +360°	
T-axis Allowable Inertia (GD <sup>2</sup> /4)		1 kg : 0.0013 kg/m² or less 3 kg : 0.017 kg/m² or less	1 kg : 0.0013 kg · m² or less 2 kg : 0.009 kg · m² or less 3 kg : 0.017 kg · m² or less	
Mass		95 kg	115 kg	
IEC Protection Class		IF	67	
Clean Class*2		ISO d	class 5	

Model	MOTOMAN-	MPP3S MPP3H	
Ambient Conditions	Temperature	0°C to +40°C	
	Humidity	20% to 80%RH (non-condensing)	
	Vibration	4.9 m/s <sup>2</sup> (0.5G) or less	
		• Free from corrosive gas or liquid, or	
	Others	explosive gas or liquid	
		<ul> <li>Free from excess</li> </ul>	ive electrical noise
		(plasma)	
Power Requirements*3		1.5	kVA

\*1 : Conforms to ISO 9283.

\*2 : Cleanroom standards: ISO14644-1

MPP3S and MPP3H are certified for cleanroom application by Fraunhofer IPA. \*3 : Varies in accordance with applications and motion patterns.

\*4 : Recommended range of motion is 1040 mm (dia.)  $\times$  300 mm (H).

T-axis unit may vibrate when it moves outside the recommended range of motion. \*5: With a limit in continuous operations

(No continuous operation limit: 185 cpm or less)

Note: SI units are used for the specifications.



# MOTOMAN-MPK50II

50 kg payload, R1893 mm maximum reach DX200

Dimensions Units : mm . T-point Maximum Envelope





Tube for field bus cables (ID=12 mm) (Robot base) Air inlet (A, B)  $2 \times PT3/8$ with pipe plug



Connector for internal user I/O wiring harness (Base side): JL05-2A24-28PC (with cap) Matching connector: JL05-6A24-28S (provided by users)

View B



#### R680 1324 155 200 800 1442 1297 1227 1014.5 Т P-point 800 506 508.5 1653.5 T-point 752 22 Tapped holes M12 (4 holes) 105 427 600 (Depth: 20) 260 в 0∢ 210 198 S 893 621 701

### Manipulator Specifications

	• •				
Model		MOTOMAN-MPK50II	Allowable Inertia	T avia (wriat twiat)	$5.5 kam^2$
Туре		YR-MPK0050-J00	(GD <sup>2</sup> /4)	5.5 kg m	
Controlled Axis		4 (vertically articulated)	Mass		670 kg
Payload		50 kg		Temperature	0℃ to +45℃
Repeatabili	ty*1	±0.5 mm		Humidity	20% to 80%RH (non-condensing)
	S-axis (turning)	-180° - +180°	Anabiant	Vibration	4.9 m/s <sup>2</sup> (0.5G) or less
Range of	L-axis (lower arm)	-35° - +80°	Amplent		<ul> <li>Free from corrosive gas or liquid, or</li> </ul>
Motion	U-axis (upper arm)	-105° - +15°	Conditions	Othoro	explosive gas or liquid
	T-axis (wrist twist)	-350° - +350°		Others	<ul> <li>Free from exposure to water, oil, or dust</li> </ul>
	S-axis (turning)	3.23 rad/s, 185°/s			<ul> <li>Free from excessive electrical noise (plasma)</li> </ul>
Maximum	L-axis (lower arm)	3.75 rad/s, 215°/s	Power Require	ements*2	4.0 kVA
Speed	U-axis (upper arm)	3.75 rad/s, 215°/s	*1:Conforms	to ISO 9283.	
	T-axis (wrist twist)	6.53 rad/s, 374°/s	*2 : Varies in accordance with applications and motion patterns.		
			Note: SI units a	are used for the specifi	cations.

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# **FS100 CONTROLLER**

### FS100 Controller Specifications

Items	Specifications
Configuration	Open structure (IP20)
Dimensions	470 (W)×420 (D)×200 (H) mm (Does not include protruding parts.)(Possible to control two external axes)
Mass	20 kg
Manipulator	MOTOMAN-MPP3S, -MPP3H, -MPK2F, -MPK2F-5
Cooling System	Direct cooling
Ambient	During operation: 0°C to +40°C
Temperature	During storage ∶-10°C to +60°C
Relative Humidity	90% max. (non-condensing)
Power Supply	Three-phase 200/220 VAC (+10% to -15%), 50/60 Hz
Grounding	Grounding resistance: 100 $\Omega$ or less
	Specialized signals: 10 inputs and 1 output
Digital I/Os	General signals : 28 inputs and 28 outputs
	Max. I/O (optional) : 1024 inputs and 1024 outputs
Positioning System	Serial communications (absolute encoder)
Programming	JOB: 10,000 steps, 1,000 instructions
Capacity	CIO ladder: 1,500 steps max.
Expansion Slots	MP2000 bus × 5 slots
LAN (Connection to Host)	1 (10BASE-T/100BASE-TX)
Interface	RS-232C: 1ch
Control Method	Software servo control
Drive Lipite	For robot axes: One drive unit for AC servo with 4 to 6 axes (depend on the type)
Drive Offics	For external axes: Two more axes can be added. (Can be installed in the controller.)

### Programming Pendant Specifications Optional

Items	Specifications
Dimensions	169 (W)×50 (D)×314.5 (H) mm
Mass	0.990 kg
Material	Reinforced plastics
Operation	Select keys, axis keys (8 axes), numerical/application keys, Mode switch with key (mode: teach,
Device	play, and remote), emergency stop button, enable switch, compact flash card interface device
Device	(compact flash is optional.), USB port (1 port)
Display	640×480 pixels color LCD, touch panel
Display	(Alphanumeric characters, Chinese characters, Japanese letters, Others)
IEC Protection Class	IP65
Cable Length	Standard: 8 m, max.: 20 m (with optional extension cable)

Note: A programming pendant or a dummy connector is required with the FS100. (Sold separately.)

Programming pendant (model: JZRCR-YPP03-1)

For maintenance, the programming pendant is required. One programming pendant can be used with more than one controller. Dummy connector (model: CBL-FRC063-2)
 The dummy connector must be inserted when the programming pendant is not connected or when the software pendant is used.

# DX200 CONTROLLER

DA200 Controller Specifications		
Items	Specifications	
Configuration	Dust proof (IP54)	
Dimensions	600 (W)×520 (D)×730 (H) mm (Possible to control three external axes)	
Mass	100 kg max.	
Manipulator	MOTOMAN-MPK50II	
Cooling System	Indirect cooling	
Ambient	During operation: 0°C to +45°C	
Temperature	During storage : -10°C to +60°C	
Relative Humidity	90% max. (non-condensing)	
	Three-phase 200 VAC (+10% to -15%), 50/60 Hz (±2%)	
Power Supply	Three-phase 220 VAC (+10% to -15%), 60 Hz (±2%)	
Grounding	Grounding resistance: 100 $\Omega$ or less	
	Specialized signals: 28 inputs and 7 outputs	
Digital I/Os	General signals : 40 inputs and 40 outputs	
	Max. I/O (optional) : 4096 inputs and 4096 outputs	
Positioning System	Serial communications (absolute encoder)	
Programming	JOB: 200,000 steps, 10,000 instructions	
Capacity	CIO ladder: 20,000 steps max.	
Expansion Slots	PCI: 2 slots	
LAN (Connection to Host)	1 (10BASE-T/100BASE-TX)	
Interface	RS-232C: 1ch	
Control Method	Software servo control	
Drive Units	SERVOPACK for AC servomotors (can control up to 9 axes)	

### DX200 Controller Specifications

# Programming Pendant Specifications

Items	Specifications		
Dimensions	169 (W)×50 (D)×314.5 (H) mm		
Mass	0.990 kg		
Material	Reinforced plastics		
Operation Device	Select keys, axis keys, numerical/application keys, mode selector switch with keys (mode: teach, play, and remote), emergency stop button, enable switch, compact flash card interface device (compact flash is optional.), USB port (1 port)		
Display	5.7-inch color LCD, touch panel 640×480 pixels (Alphanumeric characters, Chinese characters, Japanese letters, Others)		
IEC Protection Class	IP65		
Cable Length	Standard: 8 m, max.: 36 m (with optional extension cable)		

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**YASKAWA ELECTRIC CORPORATION** 

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